

# Online Supplement for “The Shortest-Path Problem with Resource Constraints and $k$ -Cycle Elimination for $k \geq 3$ ”

Stefan Irnich

RWTH Aachen University, Deutsche Post Lehrstuhl für Optimierung von Distributionsnetzwerken,  
Templergraben 64, 52062 Aachen, Germany, sirnich@or.rwth-aachen.de

Daniel Villeneuve

AD OPT Technologies Inc., 3535 Queen Mary, Suite 650, Montréal, Québec, Canada H3V 1H8,  
danielv@ad-opt.com

The paper “The Shortest-Path Problem with Resource Constraints and  $k$ -Cycle Elimination for  $k \geq 3$ ” mainly focuses on the theoretical aspects of the shortest-path problem with resource constraints (SPPRC) and cycle elimination. The three examples of applying SPPRC- $k$ -cyc to solve VRPTW subproblems were meant to show the relevance of SPPRC- $k$ -cyc and not meant as a detailed computational study on VRPTW.

The online supplement can be viewed as a complement to the theoretical work presented in the paper. It gives a detailed analysis of the proposed method for the well-known Solomon (1987) benchmark problems of VRPTW. The online supplement contains a comparison of lower bounds and computation times for 168 different VRPTW instances ranging from 25 to 100 customers.

*Key words:* shortest paths; cycle elimination; column generation; vehicle routing

*History:* Accepted by William J. Cook, Area Editor for Design and Analysis of Algorithms; received August 2003; revised May 2004; accepted August 2004.

---

## 1. Extended Computational Results

We start with a description of Solomon’s (1987) benchmark problems, give references to the branch-and-price methodology as well as techniques to speed up and improve the solution process. The main part presents the numerical results and discusses the outcome.

### 1.1. The Solomon Instances

For the computational study, we have used Solomon’s (1987) benchmark problems and the same setup as in Kohl et al. (1999), Larsen (1999), and Rich (1999). There are two series of

problems, one with approximately 5 to 10 customers per route (type 1) and a second one with long routes with sometimes more than 25 customers in a route (type 2). Within each series, there are three different types of problems, i.e. C-problems, R-problems, and RC-problems where customers are located in clusters (C), randomly (R), and partly in clusters and partly randomly (RC). Hence, there are six groups of problems referred to as (C1, R1, RC1, C2, R2, RC2) with 56 instances. In addition to these original 100 customer problems, instances with 25 and 50 customers are created by considering only the first 25, resp. 50, customers. This leads to a test suite of 168 instances.

As in most papers on exact methods for Solomon’s problems the objective is to minimize the total cost, i.e. the travelled distance. Travel times and distances are rounded with a precision of one position after decimal point, see Kohl et al. (1999, page 111). In contrast to this, papers on VRPTW heuristics use unrounded distances and times, and try to minimize the number of routes as the main objective.

It is generally accepted that VRPTW instances with long routes are much harder to solve than the ones with shorter routes. Nevertheless, there are still seven unsolved Solomon benchmark problems with short routes (r104.100, r108.100, r112.100, rc104.100, rc106.100, rc107.100, rc108.100). As reported in Cordeau et al. (2002), there are 35 unsolved problems in the second set, even with 25 and 50 customers and one clustered instance c204.100.

## 1.2. Branch-and-Price Solution Methodology for the VRPTW

126 of these 168 Solomon problems could previously be solved to optimality, see Cordeau et al. (2002). As far as we know, all of these successfully solved instances can be solved by column generation techniques. From this point of view, column generation and its integration into a branch-and-bound framework (branch-and-price) seems to be the best method at hand. Nevertheless, the idea of  $k$ -cycle elimination can analogously be applied to price-directive decomposition approaches based on Lagrangean relaxation, see e.g. Kallehauge et al. (2001).

For the sake of brevity, we do not give an overview of different models and methodologies for the VRPTW here, but refer the reader to the survey paper Cordeau et al. (2002). General references to column generation or branch-and-price are Wolsey (1998) and Barnhart et al. (1998).

Several techniques to improve a standard branch-and-price approach for VRPTW have been published. We use the following ideas:

- Pre-processing, see e.g. Desrochers et al. (1992): Resource window reduction and arc elimination.
- In order to make the costs  $c_{ij}$  and the times  $t_{ij}$  fulfill the triangle inequality, an offset of 0.1 is added to all cost coefficients  $c_{ij}$  except for the start depot  $i = s$ . The offset does not change the optimal solution and all results can be substituted back by subtracting  $0.1 \cdot n$  from the objective, see also Kohl et al. (1999).
- $f$ -path cuts: The basic idea is to integrate cutting plane methods into the column generation technique (sometimes called 'branch-and-price-and-cut').  $f$ -path cuts are valid inequalities for the VRPTW which are added to the RMP when a violated inequality is detected. 2-path cuts have been identified as one key approach to improve the column generation lower bound, see e.g. Kohl (1995), Kohl et al. (1999), and Rich (1999). Their separation subproblem is not trivial but requires the solution of a TSPTW on the corresponding subset of nodes  $S$ .

In our implementation, we use similar techniques as Rich (1999), i.e. Karger's probabilistic algorithm (Karger 1993, Karger and Stein 1993) to identify customer sets  $S$  with small flows  $x(S)$  and a dynamic programming algorithm for the TSPTW, see e.g. Dumas et al. (1995). We separate 1-path cuts and 2-path cuts only at the root node of the branch-and-bound tree.

- Nearest neighbor networks for *partial pricing*, see Gamache et al. (1999), in Larsen (1999) called *limited subsequence*:

The pricing problem has to compute at least one new route with negative reduced cost as long as there exists one. By replacing the network  $G$  with its smaller  $\ell$ -nearest neighbor network  $G_\ell$ , the pricing problem on  $G_\ell$  is a smaller problem. We work with a hierarchy of three networks  $G_5$ ,  $G_{10}$  and the complete network  $G$ . Pricing is firstly done in  $G_5$ , if this fails, pricing is done on  $G_{10}$  and if this also fails, the complete pricing is done on  $G$ . We always add the arcs  $(0, i)$  and  $(i, n + 1)$  which connect the depot with all customers to  $G_\ell$ .

- Branching is first done on the number of vehicles (if the number of routes is fractional) and on arcs secondly. We choose the arc  $(i, j) \in A$  with fractional flow  $x_{ij}$  which maximizes  $c_{ij} \cdot \min(x_{ij}, 1 - x_{ij})$ . But there is one exception from this branching rule.

Within the branch-and-bound tree, solving instances with the additional constraint that the number of vehicles (after branching) has to be equal to one is sometimes very hard. We observed that the corresponding nodes of the branch-and-bound tree had huge computation times and sometimes we were not able to solve them (within the given time limit).

In order to overcome this problem we used the following strategy: Whenever a solution of the RMP has a fractional number of vehicles  $\#veh$  with  $1 < \#veh < 2$  we do not branch on the number of vehicles but on arcs.

In order to keep the number of branch-and-bound nodes to explore as small as possible, we implemented the following rule. Within branch-and-bound a *best-first* node selection strategy is used. It means that among all unsolved nodes we choose one with currently minimum lower bound (note that each son node gets an initial lower bound from its father before that node is solved by column generation).

### 1.3. Comparison of 2-, 3-, and 4-Cycle Elimination

All computations were performed on a standard PC with Intel Pentium III, 600MHz with 512MB main memory. The algorithm is coded in C++ and the callable library of CPLEX 7.0 CPLEX (1997) is used to solve the restricted master problem (RMP).

#### 1.3.1. Comparison with a Restricted Computing Time of 1 Hour

We start with a detailed analysis of the lower bounds for  $k$ -cycle elimination with  $k \in \{2, 3, 4\}$ . The computation time for each instance is restricted to one hour (=3600 seconds). The Tables 1–3 contain the following information:

- The name of the *instance* is given in the first column.
- The *integrality gap* of the instance is the interval  $[lb_1(1) : opt]$  given by the lower bound  $lb_1(1)$  computed *without* cycle-elimination (a plain SPPRC subproblem solver) and the objective  $opt$  of an optimal solution. In case the optimum  $opt$  is not known, we give a valid upper bound  $ub$  computed by a heuristic algorithm<sup>1</sup> and mark that entry with  $ub^*$ .

---

<sup>1</sup>Special thanks to Birger Funke who computed the upper bounds for some of the hard Solomon benchmark instances with methods described in Funke (2003).

- Three compound sections are given for  $k = 2$ ,  $k = 3$ , and  $k = 4$ , and describe the outcome of the branch-and-price procedure with the SPPRC- $k$ -cyc subproblem solver.
- $lb_1(k)$  is the lower bound implied by the LP-relaxation of the master program before cutting planes are added. For some instances and different values of  $k$  we were not able to solve the LP-relaxation of the master program to optimality. This fact is indicated by an entry ‘-’.
- $lb_2(k)$  is the lower bound after adding 1-path cuts and 2-path cuts. If  $lb_1(k)$  and  $lb_2(k)$  are identical to  $lb_1(k-1)$  and  $lb_2(k-1)$  for  $k \geq 3$  we do not print the same information again.
- Whenever we are not able to solve the instance to optimality the entry  $lb(k)$  gives the computed lower bound at the moment when the computation was stopped (3600s).
- The size of the branch-and-price search is given by the number of *tree* nodes. For instances not solved to optimality, this column indicates the number of the tree nodes evaluated within one hour.
- $T(k)$  gives the time for completing the computation or  $TL$  (=time limit) when the computation was stopped after 3600s.

A comparison of the detailed results for  $k$ -cycle elimination given in the Tables 1–3 can be aggregated to the following characteristic numbers:

How many instances are solved to optimality with $k = 2$ ?	112
How many instances are solved to optimality with $k = 3$ ?	117
How many instances are solved to optimality with $k = 4$ ?	117
How many instances are solved to optimality with $k \in \{2, 3, 4\}$ ?	124
How often is $k = 3$ optimal but $k = 2$ not optimal?	7
How often is $k = 4$ optimal but $k = 3$ not optimal?	5
How often is $k = 4$ optimal but $k = 2$ not optimal?	11
How often is $k = 2$ optimal but neither $k = 3$ nor $k = 4$ optimal?	2
How often is time $T(3)$ smaller than $T(2)$ ?	42
How often is time $T(4)$ smaller than $T(3)$ ?	17
How often is time $T(4)$ smaller than $T(2)$ ?	41
How often is $T(3)$ or $T(4)$ smaller than $T(2)$ ?	47

Comparing the results for  $k = 3$  and  $k = 4$  against  $k = 2$  shows that 3-cycle and 4-cycle elimination are successful only for some instances. “Successful” means, that improved

Table 1: Results for Solomon Benchmark Problems with 25 Customers

Instance	Integrality Gap	k=2			k=3			k=4			Time
		b <sub>1</sub> (2)	b <sub>2</sub> (2)	Tree	b <sub>1</sub> (3)	b <sub>2</sub> (3)	Tree	b <sub>1</sub> (4)	b <sub>2</sub> (4)	Tree	
C101.25	[191.3	191.3	191.3	1	opt	1	opt	1	opt	1	0.5
C102.25	[189.15 : 190.3]	190.3	190.3	1	opt	1	opt	1	opt	1	0.5
C103.25	[189.15 : 190.3]	190.3	190.3	1	opt	1	opt	1	opt	1	1.8
C104.25	[185.75 : 186.9]	186.9	186.9	1	opt	1	opt	1	opt	1	2.8
C105.25	[191.3	191.3	191.3	1	opt	1	opt	1	opt	1	0.4
C106.25	[191.3	191.3	191.3	1	opt	1	opt	1	opt	1	0.4
C107.25	[191.3	191.3	191.3	1	opt	1	opt	1	opt	1	0.4
C108.25	[190.5 : 191.3]	191.3	191.3	1	opt	1	opt	1	opt	1	0.6
C109.25	[188.46 : 191.3]	191.3	191.3	1	opt	1	opt	1	opt	1	0.4
R101.25	[617.1	617.1	617.1	1	opt	1	opt	1	opt	1	1.8
R102.25	[546.333 : 547.1]	547.1	547.1	2	opt	2	opt	2	opt	2	0.1
R103.25	[454.067 : 454.6]	454.6	454.6	1	opt	1	opt	1	opt	1	0.4
R104.25	[414.85 : 416.9]	416.9	416.9	1	opt	1	opt	1	opt	1	0.3
R105.25	[530.5	530.5	530.5	1	opt	1	opt	1	opt	1	0.6
R106.25	[457.3 : 465.4]	465.4	465.4	1	opt	1	opt	1	opt	1	0.1
R107.25	[415.125 : 424.3]	424.3	424.3	2	opt	2	opt	2	opt	2	1.3
R108.25	[389.424 : 397.3]	396.139	396.139	3	opt	3	opt	3	opt	3	0.3
R109.25	[439.425 : 441.3]	441.3	441.3	1	opt	1	opt	1	opt	1	6.2
R110.25	[419.072 : 444.1]	437.3	437.363	27	opt	9	opt	9	opt	9	5.0
R111.25	[412.815 : 428.8]	423.788	428.05	6	opt	5	opt	4	opt	4	3.1
R112.25	[365.03 : 393]	384.2	385.391	11	opt	11	opt	10	opt	10	18.0
RC101.25	[390.15 : 461.1]	406.625	461.1	2	opt	2	opt	2	opt	2	1.1
RC102.25	[347.067 : 351.8]	351.8	351.8	1	opt	1	opt	1	opt	1	0.4
RC103.25	[317.538 : 332.8]	332.05	332.05	3	opt	3	opt	3	opt	3	1.8
RC104.25	[299.066 : 306.6]	305.825	305.825	5	opt	5	opt	5	opt	5	3.6
RC105.25	[408.525 : 411.3]	410.95	410.95	3	opt	3	opt	3	opt	3	1.1
RC106.25	[319.661 : 345.5]	342.829	343.2	10	opt	10	opt	10	opt	10	2.3
RC107.25	[292.947 : 298.3]	298.3	298.3	1	opt	1	opt	1	opt	1	0.6
RC108.25	[286.565 : 284.5]	293.791	294.5	2	opt	2	opt	2	opt	2	0.7
C201.25	[214.7	214.7	214.7	1	opt	1	opt	1	opt	1	1.8
C202.25	[214.7	214.7	214.7	1	opt	1	opt	1	opt	1	2.3
C203.25	[213.775 : 214.7]	214.7	214.7	1	opt	1	opt	1	opt	1	7.0
C204.25	[207.156 : 213.1]	210.992	211.046	11	opt	11	opt	10	opt	10	7.9
C205.25	[196.525 : 214.7]	212.05	214.7	3	opt	3	opt	3	opt	3	392.3
C206.25	[194.015 : 214.7]	197.7	214.7	4	opt	4	opt	4	opt	4	1.4
C207.25	[200.442 : 214.5]	207.981	214.4	14	opt	14	opt	12	opt	12	2.4
C208.25	[183.845 : 214.5]	193.28	214.5	6	opt	6	opt	5	opt	5	36.9
R201.25	[448.5 : 463.3]	460.1	460.1	3	opt	3	opt	3	opt	3	4.3
R202.25	[374.117 : 410.5]	406.35	408.35	6	opt	6	opt	6	opt	6	2.0
R203.25	[337.51 : 391.4]	379.882	381.625	46	opt	46	opt	46	opt	46	0.8
R204.25	[304.246 : 355]	333.075	335.35	622	opt	622	opt	622	opt	622	55.2
R205.25	[365.475 : 393]	381.283	388.45	16	opt	16	opt	16	opt	16	3523.7
R206.25	[317.98 : 374.4]	363.132	365.908	75	opt	75	opt	75	opt	75	9.7
R207.25	[309.609 : 361.6]	347.592	349.741	179	opt	179	opt	179	opt	179	268.4
R208.25	[295.923 : 328.2]	318.105	318.922	75	opt	75	opt	75	opt	75	986.1
R209.25	[327.253 : 370.7]	353.875	358.321	46	opt	46	opt	46	opt	46	1861.9
R210.25	[340.505 : 404.6]	395.844	397.906	56	opt	56	opt	56	opt	56	72.2
R211.25	[299.998 : 350.9]	330.14	330.466	695	opt	695	opt	695	opt	695	403.6
RC201.25	[315.853 : 360.2]	356.65	360.2	2	opt	2	opt	2	opt	2	TL
RC202.25	[234.629 : 338]	290.408	312.992	130	opt	130	opt	130	opt	130	950.4
RC203.25	[185.477 : 326.9]	213.508	260.385	218	opt	218	opt	218	opt	218	TL
RC204.25	[169.544 : 299.7]	188.213	244.71	131	opt	131	opt	131	opt	131	TL
RC205.25	[258.961 : 338]	307.6	320.787	42	opt	42	opt	42	opt	42	57.9
RC206.25	[198.363 : 324]	249.2	288.978	300	opt	300	opt	300	opt	300	TL
RC207.25	[175.003 : 298.3]	216.67	263.894	346	opt	346	opt	346	opt	346	TL
RC208.25	[155.514 : 269.1*]	169.671	233.078	89	opt	89	opt	89	opt	89	TL

Table 2: Results for Solomon Benchmark Problems with 50 Customers

Instance	Integrality Gap	$k=2$			$k=3$			$k=4$			Time		
		$b_1(2)$	$b_2(2)$	Tree	Time	$b_1(3)$	$b_2(3)$	Tree	Time	$b_1(4)$		$b_2(4)$	Tree
C101-50	362,4	362,4	362,4	opt	1	3,2	opt	1	3,2	opt	1	3,2	3,2
C102-50	[360,25 : 361,4]	361,4	361,4	opt	1	7,0	opt	1	7,2	opt	1	15,7	15,7
C103-50	[360,25 : 361,4]	361,4	361,4	opt	1	13,4	opt	1	31,5	opt	1	139,9	139,9
C104-50	[354,021 : 358]	357,25	358	opt	3	67,2	opt	1	161,0	opt	1	2151,6	2151,6
C105-50	362,4	362,4	362,4	opt	1	4,1	opt	1	4,2	opt	1	4,2	4,2
C106-50	362,4	362,4	362,4	opt	1	3,2	opt	1	3,3	opt	1	3,3	3,3
C107-50	362,4	362,4	362,4	opt	1	3,9	opt	1	3,9	opt	1	4,0	4,0
C108-50	[361,81 : 362,4]	362,4	362,4	opt	1	5,7	opt	1	5,5	opt	1	5,8	5,8
C109-50	[359,365 : 362,4]	362,4	362,4	opt	1	5,6	opt	1	12,6	opt	1	19,7	19,7
R101-50	[1043,37 : 1044]	1043,37	1044	opt	2	3,1	opt	2	3,2	opt	2	3,1	3,1
R102-50	909	909	909	opt	1	1,7	opt	1	1,7	opt	1	1,5	1,5
R103-50	[756,117 : 772,9]	765,95	767,3	opt	32	35,3	opt	17	33,4	opt	16	38,8	38,8
R104-50	[608,521 : 625,4]	616,5	620,758	opt	34	212,6	opt	24	353,9	opt	16	1438,0	1438,0
R105-50	[890,187 : 899,3]	892,12	893,65	opt	8	11,9	opt	8	11,9	opt	8	11,9	11,9
R106-50	[789,433 : 793]	791,367	793	opt	2	8,6	opt	2	8,9	opt	2	9,1	9,1
R107-50	[697,767 : 711,1]	704,438	705,88	opt	31	61,5	opt	22	55,8	opt	22	88,9	88,9
R108-50	[578,482 : 617,7]	588,926	595,177	opt	197	148,4	opt	141	100,9	opt	141	102,2	102,2
R109-50	[727,515 : 786,8]	775,096	776,231	opt	16	26,4	opt	17	54,1	opt	11	40,1	40,1
R110-50	[675,457 : 697]	692,577	694,15	opt	210	300,6	opt	109	227,3	opt	117	334,3	334,3
R111-50	[658,752 : 707,2]	691,812	692,642	opt	693	211	opt	659	3522,8	opt	233	33,4	33,4
R112-50	[582,715 : 630,2]	607,219	612,36	opt	4	26,4	opt	4	26,0	opt	4	26,1	26,1
RC101-50	[826,613 : 944]	850,021	944	opt	143	303,8	opt	155	317,1	opt	160	359,5	359,5
RC102-50	[706,606 : 822,5]	719,902	813,037	opt	12	90,0	opt	11	90,0	opt	12	150,9	150,9
RC103-50	[612,24 : 710,9]	643,133	710,667	opt	19	68,5	opt	3	77,8	opt	1	465,2	465,2
RC104-50	[527,171 : 545,8]	543,75	543,75	opt	19	64,9	opt	12	54,8	opt	12	58,7	58,7
RC105-50	[746,314 : 855,3]	754,443	853,675	opt	19	64,9	opt	22	50,2	opt	16	40,1	40,1
RC106-50	[633,228 : 723,2]	664,433	717,155	opt	50	93,7	opt	23	167,5	opt	19	609,1	609,1
RC107-50	[633,228 : 723,2]	591,476	632,336	opt	33	877,1	opt	9	666,6	opt	6	17,1	17,1
RC108-50	[570,685 : 642,7]	538,957	590,469	opt	1	16,8	opt	1	233,6	opt	1	771,8	771,8
C201-50	360,2	360,2	360,2	opt	1	196,8	opt	1	859,4	opt	1	2655,4	2655,4
C202-50	360,2	360,2	360,2	opt	1	228,4	opt	1	1159,4	opt	1	38,7	38,7
C203-50	359,8	359,8	359,8	opt	4	222,4	opt	4	567,4	opt	1	108,9	108,9
C204-50	[347,392 : 350,1]	357,35	359	opt	6	274,0	opt	4	386,8	opt	1	1512,5	1512,5
C205-50	[341,762 : 359,8]	344,2	359	opt	2	138,5	opt	1	307,6	opt	1	662,5	662,5
C206-50	[338,518 : 359,8]	356,269	359,6	opt	2	13,3	opt	1	6,4	opt	1	47,8	47,8
C207-50	[348,625 : 359,6]	340,425	350,5	opt	8	66,1	opt	23	470,4	opt	5	665,9	665,9
C208-50	[331,27 : 350,5]	788,425	791,9	opt	134	603,98	opt	37	3498,4	opt	13	1091,4	1091,4
R201-50	[754,098 : 791,9]	692,737	696,525	opt	35	274,0	opt	295	3498,4	opt	137	1091,4	1091,4
R202-50	[637,594 : 698,5]	590,933	593,43	opt	170	597,81	opt	179	530,59	opt	77	628,31	628,31
R203-50	[538,526 : 605,3]	474,562	482,324	opt	166	485,031	opt	165	641,03	opt	78	255,4	255,4
R204-50	[440,989 : 506,4]	474,562	482,324	opt	146	630,673	opt	165	641,03	opt	78	255,4	255,4
R205-50	[595,553 : 690,1]	666,604	672,351	opt	160	519,989	opt	179	530,59	opt	62	1438,0	1438,0
R206-50	[530,574 : 632,4]	609,59	611,363	opt	15	51,5	opt	8	30,6	opt	28	500,3	500,3
R207-50	[467,314 : 575,5*]	538,762	544,324	opt	15	47,8	opt	15	47,8	opt	12	53,2	53,2
R208-50	[??? : 487,7*]	462,406	471,563	opt	22	408,496	opt	38	516,14	opt	28	500,3	500,3
R209-50	[535,279 : 600,6]	582,877	588,413	opt	10	411,691	opt	6	729,9	opt	5	82,4	82,4
R210-50	[532,119 : 645,6]	624,155	624,162	opt	65	581,528	opt	62	594,483	opt	62	934,9	934,9
R211-50	[457,426 : 535,5]	507,95	512,558	opt	46	441,336	opt	38	492,94	opt	28	500,3	500,3
RC201-50	[530,547 : 684,8]	670,15	681,983	opt	36	390,822	opt	31	456,133	opt	28	500,3	500,3
RC202-50	[416,67 : 613,6]	494,608	546,359	opt	36	480,352	opt	31	456,133	opt	28	500,3	500,3
RC203-50	[326,429 : 555,3]	408,496	490,122	opt	19	418,52	opt	15	424,86	opt	15	424,86	424,86
RC204-50	[??? : 444,2*]	314,447	406,094	opt	10	411,691	opt	6	729,9	opt	5	82,4	82,4
RC205-50	[481,604 : 630,2]	541,592	581,528	opt	65	581,528	opt	62	594,483	opt	62	934,9	934,9
RC206-50	[363,874 : 610]	441,336	532,959	opt	46	441,336	opt	38	492,94	opt	28	500,3	500,3
RC207-50	[333,105 : 558,6*]	390,822	469,64	opt	36	390,822	opt	31	456,133	opt	28	500,3	500,3
RC208-50	[264,761 : 479,2*]	316,325	416,051	opt	19	418,52	opt	15	424,86	opt	15	424,86	424,86

Table 3: Results for Solomon Benchmark Problems with 100 Customers

Instance	Integrality Gap	k=2			k=3			k=4			Time
		b <sub>1</sub> (2)	b <sub>2</sub> (2)	b(2)	b <sub>1</sub> (3)	b <sub>2</sub> (3)	b(3)	b <sub>1</sub> (4)	b <sub>2</sub> (4)	b(4)	
C101	827.3	827.3	827.3	opt	1	30.4	opt	1	opt	1	30.4
C102	827.3	827.3	827.3	opt	1	56.9	opt	1	opt	1	77.0
C103	826.3	826.3	826.3	opt	1	130.4	opt	1	opt	1	339.5
C104	[822,389 : 822,9]	822.9	822.9	opt	1	358.5	opt	1	opt	1	1533.8
C105	827.3	827.3	827.3	opt	1	35.6	opt	1	opt	1	36.1
C106	827.3	827.3	827.3	opt	1	35.0	opt	1	opt	1	39.7
C107	827.3	827.3	827.3	opt	1	34.5	opt	1	opt	1	35.1
C108	[820,988 : 827.3]	827.3	827.3	opt	1	49.0	opt	1	opt	1	60.3
C109	[817,485 : 827.3]	827.3	827.3	opt	2	190.2	opt	1	opt	1	163.0
R101	[1631,15 : 1637,7]	1634	1634	opt	12	115.8	opt	12	opt	12	117.6
R102	1466.6	1466.6	1466.6	opt	1	21.8	opt	1	opt	1	24.2
R103	[1203,24 : 1208,7]	1206.42	1206.42	opt	26	446.1	1206.57	20	opt	20	499.8
R104	[937,062 : 971,5]	949,103	951,101	959,08	77	358.3	955,705	44	opt	44	361.7
R105	[1341,19 : 1355,3]	1346,14	1349,32	opt	47	2132.8	opt	206	opt	206	2182.0
R106	[1212,27 : 1234,6]	1226,44	1227,4	opt	204	1063.4	opt	140	opt	140	1052.23
R107	[1036,96 : 1064,6]	1051,84	1052,94	1063,4	182	918,97	1053,4	919,89	1063,2	140	911,493
R108	[891,646 : 939*]	907,162	910,617	918,97	94	1139,8	913,449	1143,1	913,85	36	1134,28
R109	[1097,46 : 1146,9]	1130,59	1133,16	1139,8	307	1058,8	1134,93	1061	1135,06	349	1055,33
R110	[1021,33 : 1068]	1048,48	1049,94	1058,8	203	1044	1052,52	1061	1055,75	101	1034,25
R111	[1005,88 : 1048,7]	1032,03	1032,07	1044	241	928,55	1034,23	1044,4	1034,35	82	1034,25
R112	[892,545 : 960,5*]	919,192	922,412	928,55	91	14	923,575	925,811	1042,7	11	928,37
RC101	[1567,45 : 1619,8]	1584,09	1617,4	opt	14	462.9	opt	14	opt	14	464.7
RC102	[1380,21 : 1457,4]	1403,65	1439,55	1449	161	1247,8	1440,66	1450,5	1450,5	154	1405,05
RC103	[1170,32 : 1258]	1218,5	1241,72	1247,8	75	1113	1221,73	1242,33	1242,93	33	1223,53
RC104	[1052,55 : 1132,3]	1094,33	1112,35	1113	9	899.0	1097,17	1114,33	1114,33	6	1471,83
RC105	[1453,89 : 1513,7]	1474,16	1509,8	opt	25	1341,86	1471,83	1341,86	1353,2	17	1317,17
RC106	[1248,96 : 1373,9*]	1308,78	1333,38	1346,6	237	1187,96	1317,17	1195	1354,8	197	1318,8
RC107	[1117,32 : 1207,8]	1170,69	1186,43	1195,3	151	1066,77	1187,96	1195	1202,5	158	1182,5
RC108	[1035,93 : 1114,2]	1063,01	1097,26	1101,5	66	100,9	1100,5	1103,9	1201,8	78	11182,5
C201	589,1	589,1	589,1	opt	1	99.8	opt	1	opt	1	100.9
C202	589,1	589,1	589,1	opt	1	585.6	opt	1	opt	1	753.4
C203	[585,767 : 588,7]	588,7	588,7	opt	1	1706.3	opt	1	opt	1	1706.3
C204	[582,226 : 588,1]	588,7	588,7	opt	1	328.3	opt	1	opt	1	328.3
C205	[582,362 : 586,4]	586,4	586,4	opt	1	263.1	opt	1	opt	1	221.9
C206	[576,032 : 586]	585,4	586	opt	2	2068,8	585,131	2068,8	opt	4	814,4
C207	[571,069 : 585,8]	581,969	585,8	opt	5	2183,3	585,8	opt	opt	1	2348,8
C208	[570,461 : 585,8]	581,767	585,8	opt	2	1140	1140	1140	opt	1	1140,3
R201	[1080,74 : 1143,2]	1136,22	1138,65	1141,4	34	833,926	834,37	835,87	1140,3	35	3537,2
R202	[933,494 : 1038,4*]	1004,05	1013,69	1018	14	1117,93	1050,9	1054,99	1255,77	39	1255,77
R203	[??? : 876,5*]	846,489	847,1	847,1	4	1117,93	1117,93	1130,5	1195,38	1	1182,5
R204	[??? : 738,4*]	916,572	922,704	926,26	15	886,915	930,63	932,6	1140,3	1	1140,3
R205	[838,435 : 954,2*]	834,57	840,671	840,67	4	891,895	891,895	891,895	1255,77	1	1255,77
R206	[??? : 887,5*]	887,5	887,5	opt	1	1018	1018	1018	1018	9	1018
R207	[??? : 804,3*]	804,3	804,3	opt	1	891,895	891,895	891,895	891,895	5	891,895
R208	[??? : 703,5*]	703,5	703,5	opt	1	1018	1018	1018	1018	9	1018
R209	[750,431 : 855,7*]	819,847	823,733	826	13	1117,93	1117,93	1130,5	1195,38	1	1182,5
R210	[753,975 : 909,9*]	849,334	855,654	855,65	4	1018	1018	1018	1018	9	1018
R211	[650,812 : 756,2*]	705,806	710,744	710,74	7	1018	1018	1018	1018	9	1018
RC201	[1107,04 : 1261,8]	1240,4	1253,49	1256,5	36	1255,35	1255,35	1255,99	1255,99	44	1255,99
RC202	[880,357 : 1092,3*]	1004,05	1013,69	1018	14	1018	1018	1018	1018	9	1018
RC203	[693,611 : 934,7*]	934,7	934,7	opt	1	1018	1018	1018	1018	9	1018
RC204	[??? : 788,4*]	788,4	788,4	opt	1	1018	1018	1018	1018	9	1018
RC205	[967,076 : 1154]	1055,52	1082,05	1088,7	19	1018	1018	1018	1018	9	1018
RC206	[852,168 : 1051,1*]	952,182	982,059	984,97	12	1018	1018	1018	1018	9	1018
RC207	[768,03 : 965,9*]	866,258	877,009	877,61	9	1018	1018	1018	1018	9	1018
RC208	[??? : 776,5*]	776,5	776,5	opt	1	1018	1018	1018	1018	9	1018



lower bounds imply significantly smaller branch-and-bound trees and that smaller trees overcompensate the higher effort to solve SPPRC with  $k$ -cycle elimination (instead of solving SPPRC without or only with 2-cycle elimination). The success for only some of the instances had to be expected because not all fractional solutions of the RMPs contain routes with cycles.

A comparison of the computing times shows that 47 of the 124 solved instances are solved faster by 3- or 4-cycle elimination than with 2-cycle elimination. Ten instances (rc203.25, rc206.25, rc207.25, r112.50, r203.50, r205.50, r209.50, rc202.50, rc205.50, rc206.50) could only be solved by the new algorithms ( $k = 3, 4$ ) within one hour computing time. Five of them (r203.50, r209.50, rc202.50, rc205.50, rc206.50) were previously unsolved. The previously unsolved instance r204.25 is now solved to optimality by all of the three algorithms ( $k = 2, 3, 4$ ). This is due to the modified branching rule.

There are two instances (r204.50, c203.100) for which the new algorithms ( $k = 3, 4$ ) failed to compute the optimal solution, which are solved by using 2-cycle elimination. It seems that  $k$ -cycle elimination with  $k \geq 3$  is more successful for instances with long routes than for instances with short routes and more useful when customers are not clustered.

For some instances, especially those with long routes, the difference in the lower bounds  $lb_1(k)$  and  $lb_2(k)$  and computation times are impressive. We point out some examples.

**RC205.50** For the instance rc205.50 the lower bounds rise from  $lb_1(1) = 481.604$  to  $lb_1(2) = 541,592$ ,  $lb_1(3) = 589,313$ ,  $lb_1(4) = 621.6$  and with cutting planes from  $lb_2(2) = 581.528$  to  $lb_2(3) = 612.683$ ,  $lb_2(4) = 630.2$ . At the same time the computing times fall from  $T(2) > 3600s$  (unsolved) to  $T(3) = 729.9s$  and  $T(4) = 82.4s$ . The optimal solution with  $opt = 631.0$  is very close to the solution corresponding to 4-cycle elimination and cutting planes.

**RC202.25** Another interesting example is the instance rc202.25. The size of the branch-and-bound tree falls from 130 node for  $k = 2$  to 7 resp. 6 nodes for  $k = 3$  or  $k = 4$ . From this, a speedup of factor  $T(3)/T(2) \approx 75$  for 3-cycle elimination or of factor  $T(4)/T(2) \approx 39$  for 4-cycle elimination results.

**Visualization** In order to illustrate the difference in the computed lower bounds  $lb_1(k)$  and  $lb_2(k)$  with respect to the values of  $k \in \{2, 3, 4\}$ , it makes sense to visualize the portion

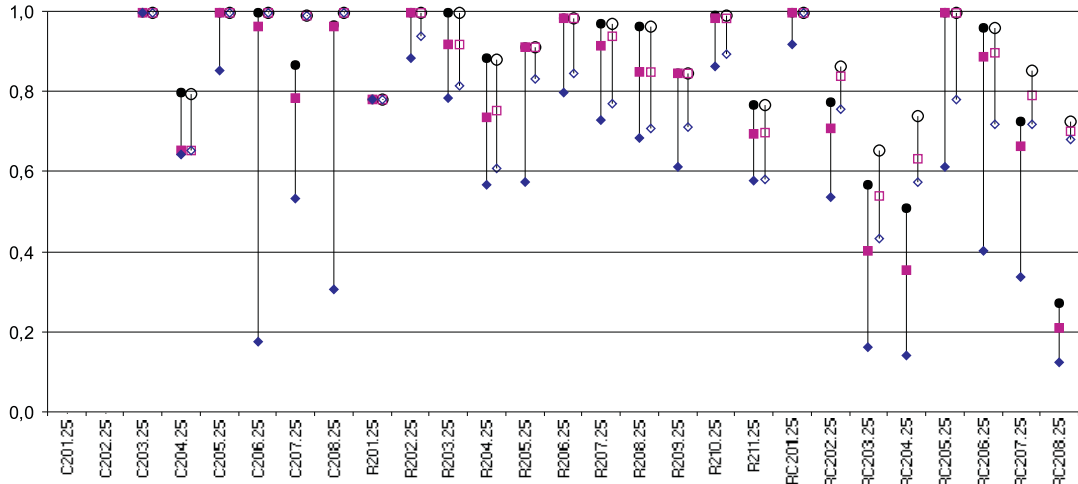


Figure 1: Results for the Solomon Problems with 25 Customers and *Long* Routes

of the integrality gap that has been closed by applying  $k$ -cycle elimination (the same measure has been used in Kohl et al. (1999) to show the effectiveness of the  $f$ -path cuts). For different values of  $k > 0$  the numbers

$$\frac{lb_1(k) - lb_1(1)}{opt - lb_1(1)} \quad \text{and} \quad \frac{lb_2(k) - lb_1(1)}{opt - lb_1(1)}$$

describe the relative portion of the integrality gap that has been closed by  $k$ -cycle elimination with/without using additional  $f$ -path cuts. Obviously, these numbers only exist when the denominator is positive, i.e. the corresponding instance has an integrality gap  $opt - lb_1(1) > 0$ . If the optimal solution is not known we use a best known upper bound  $ub^*$  instead of  $opt$ . The Figures 1–4 depict the closed portion of the integrality gap for the problems with 25 customers and long routes, all instances with 50 customers, and the instances with 100 customers and short routes. Each figure shows the portion of the integrality gap  $[lb_1(1), opt]$  resp.  $[lb_1(1), ub^*]$  which has been closed by applying  $k$ -cycle elimination. For instances with a proper positive integrality gap (up to) six values  $lb_1(k)$ ,  $lb_2(k)$  for  $k \in \{2, 3, 4\}$  are given. The three lower bounds  $lb_1(2)$ ,  $lb_1(3)$ ,  $lb_1(4)$  obtained without cutting planes as well as the three values  $lb_1(2)$ ,  $lb_1(3)$ ,  $lb_1(4)$  valid after adding  $f$ -path cuts are displayed in a line. Values for  $k = 2$  are marked with  $\blacklozenge, \diamond$ , for  $k = 3$  with  $\blacksquare, \square$ , and for  $k = 4$  with  $\bullet, \circ$ . The remaining groups of instances are not presented because there is either almost always no integrality gap (series C1, R1, and RC1 with 25 customers) or we were not able to compute many of the bounds within one hour (series C2, R2, and RC2 with 100 customers).

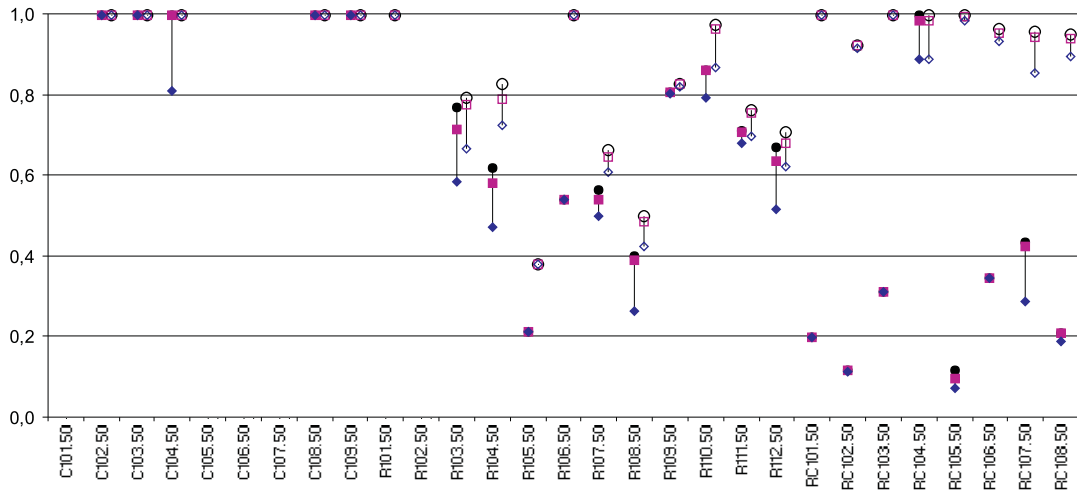


Figure 2: Results for the Solomon Problems with 50 Customers and *Short* Routes

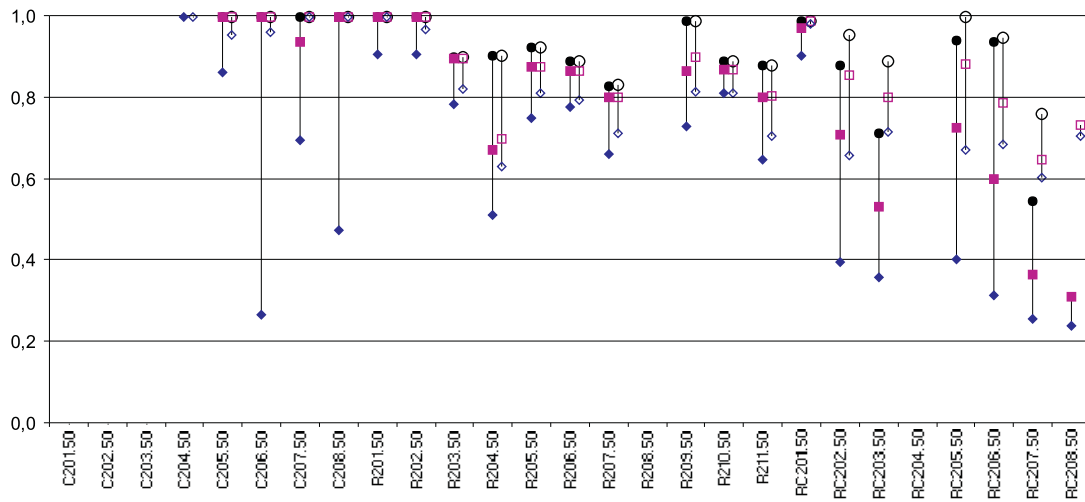


Figure 3: Results for the Solomon Problems with 50 Customers and *Long* Routes

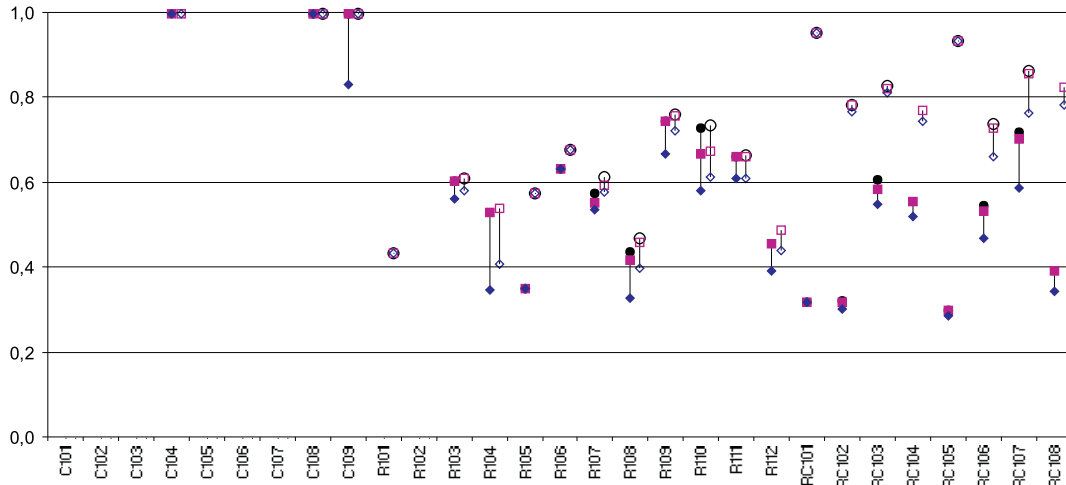


Figure 4: Results for the Solomon Problems with 100 Customers and *Short* Routes

### 1.3.2. Extensive Computational Test

The lower bounds and upper bounds given in the Tables 1–3 are useful to select some of the instances for applying the same algorithm without a time limit. Techniques for eliminating useless arcs from the graph underlying the SPPRC as described in Irnich (2004) allow for a speedup of the computations within the branch-and-bound search tree. Based on these acceleration techniques, Table 4 shows the information about optimal solutions for more than 15 previously unsolved instances from Solomon’s benchmark problems. For instances marked with \* different results have been reported in Cordeau et al. (2002). The problem c204.100 has been solved with 2-cycle elimination mainly because of extensive partial pricing

These results include four new optimal solutions for problems with short routes (series R1 and RC1). For these instances (r104.100, rc104.100, rc107.100, and rc108.100) 3-cycle elimination performs better than cycle-elimination for  $k \geq 4$ . The reason for this is that the fractional RMP solutions for  $k = 3$  contain only a small portion of routes with cycles.

For the problems of series 2 higher values of  $k$  are sometime necessary to compute strong lower bounds. The instances rc202.100, rc203.50, and rc205.100 could only be solved with very long computation times using 5-cycle elimination.

Table 4: Optimal Solutions for Previously Unsolved VRPTW Instances.

Instance	Distance	#vehicles	$k$ -cycle	Tree	Time (in s)
r104.100	971.5	11	3	5396	268106.0
rc104.100	1132.3	10	3	6757	986809.0
rc107.100	1207.8	12	3	1493	42770.7
rc108.100	1114.2	11	3	707	71263.0
c204.100	588.1	3	2	12	54254.4
r203.50	605.3	5	3	23	470.4
r204.25	355.0	2	4	35	231.7
r204.50	506.4	2	4	132	23749.5
r205.50*	690.1	4	4	137	1091.4
r206.50	632.4	4	3	1615	22455.3
r208.25*	328.2	1	3	16	363.5
r209.50	600.6	4	4	7	255.4
r210.50	645.6	4	3	960	11551.4
r211.50	535.5	3	3	1972	21323.0
rc202.50	613.6	5	4	28	503.3
rc202.100	1092.3	8	5	239	124018.0
rc203.25*	326.9	2	4	297	3455.3
rc203.50	555.3	4	5	38	54229.2
rc205.50*	630.2	5	4	5	82.4
rc205.100	1154.0	7	5	65	13295.9
rc206.50	610.0	5	4	62	934.9

## References

- Barnhart, C., E.L. Johnson, G.L. Nemhauser, M.W. Savelsbergh, P.H. Vance. 1998. Branch-and-price: column generation for solving huge integer programs. *Operations Research* **46** 316–329.
- Cordeau, J.-F., G. Desaulniers, J. Desrosiers, M.M. Solomon, F. Soumis. 2002. VRP with time windows. P. Toth, D. Vigo, eds. *The Vehicle Routing Problem*. SIAM, Philadelphia, PA. Chapter 7, 155–194.
- CPLEX 1997. Using the CPLEX Callable Library, Version 5.0. Technical report, CPLEX, Division of ILOG, Incline Village, NV.
- Desrochers, M., J. Desrosiers, M.M. Solomon. 1992. A new optimization algorithm for the vehicle routing problem with time windows. *Operations Research* **40** 342–354.
- Dumas, Y., J. Desrosiers, E. Gelinas, M.M. Solomon 1995. An optimal algorithm for the traveling salesman problem with time windows. *Operations Research* **43** 367–371.
- Funke, B. 2003. *Effiziente Lokale Suche für Vehicle Routing und Scheduling Probleme mit Ressourcenbeschränkungen*. PhD thesis, RWTH Aachen University, Aachen.
- Gamache, M., F. Soumis, G. Marquis. 1999. A column generation approach for large-scale aircrew rostering problems. *Operations Research* **47** 247–263.
- Irnich, S. (2004). Speeding up the pricing process in column generation algorithms by using reduced costs of routes to fix arcs. Technical report, Deutsche Post Lehrstuhl für Optimierung von Distributionsnetzwerken, RWTH Aachen University, Aachen. (In preparation).
- Kallehauge, B., J. Larsen, O.B.G. Madsen. 2001. Lagrangean duality applied on vehicle routing with time windows – experimental results. Technical Report IMM-TR-2001-9, Department of Mathematical Modelling, Technical University of Denmark, Lyngby, Denmark.
- Karger, D. 1993. Global min-cuts in RNC and other ramifications of a simple mincut algorithm. *Proceedings of the 4th annual ACM-SIAM Symposium on Discrete Algorithms*, ACM-SIAM. 84–93.

- Karger, D., C. Stein 1993. An  $\tilde{O}(n^2)$  algorithm for minimum cuts. *Proceedings of the 25th ACM Symposium on the Theory of Computing*, ACM-Press. 757–765.
- Kohl, N. 1995. *Exact methods for Time Constrained Routing and Related Scheduling Problems*. PhD thesis, Department of Mathematical Modelling, Technical University of Denmark, Lyngby, Denmark.
- Kohl, N., J. Desrosiers, O.B.G Madsen, M.M. Solomon, F. Soumis. 1999. 2-path cuts for the vehicle routing problem with time windows. *Transportation Science* **33** 101–116.
- Larsen, J. 1999. *Parallelization of the Vehicle Routing Problem with Time Windows*. PhD thesis, Department of Mathematical Modelling, Technical University of Denmark, Lyngby, Denmark.
- Rich, J. 1999. *A computational study of vehicle routing applications*. PhD thesis, Department of Computational and Applied Mathematics, Rice University, Houston, Texas.
- Solomon, M.M. 1987. Algorithms for the vehicle routing and scheduling problem with time window constraints. *Operations Research* **35** 254–265.
- Wolsey, L. 1998. *Integer Programming*. Wiley, Chichester, New York.